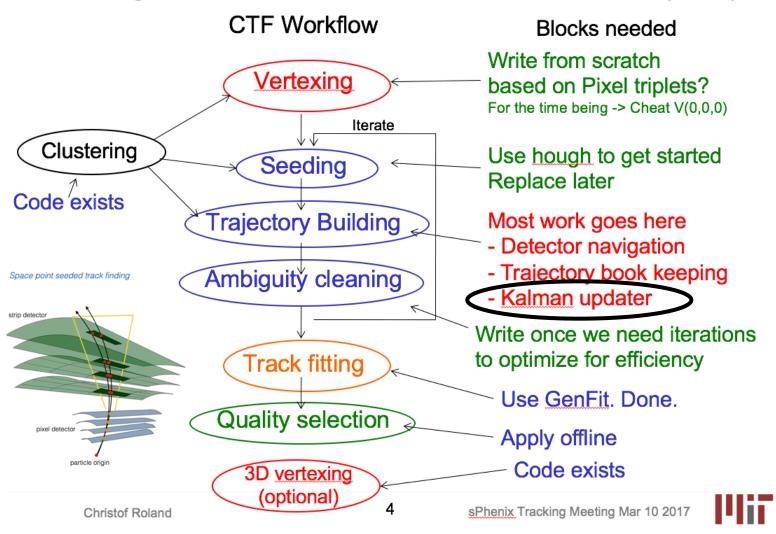


Kalman Updater

Jin Huang(BNL), Christof Roland(MIT), Haiwang Yu (NMSU)

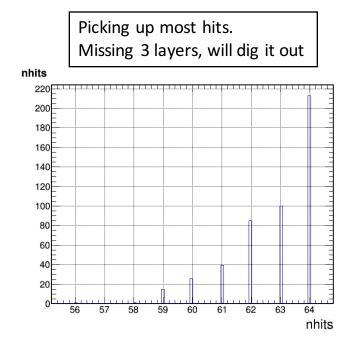
Christof's proposal

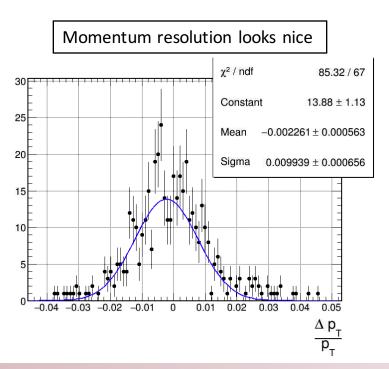
Building blocks for a combinatorial track finder (CTF)



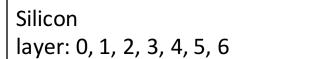
Kalman Updater

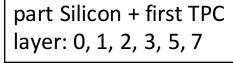
- PHGenFit::Track::updateOneMeasurementKalman
 - Spitting out tracks
- Stored cluster ID in PHGenFit::Measurement and PHGenFit::Track
- Test bench setup
 - PHG4KalmanPatRec
- Tested with single 10GeV pi+
 - cylindrical MVTX+IT+TPC
 - silicon seeding

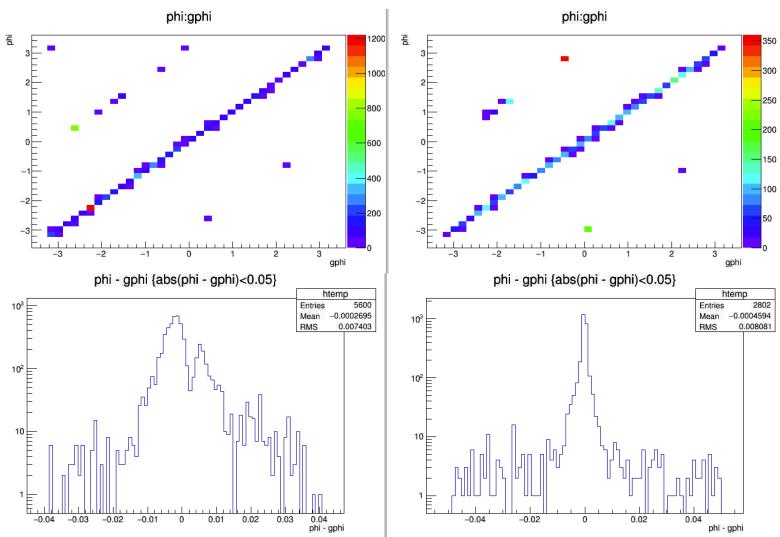




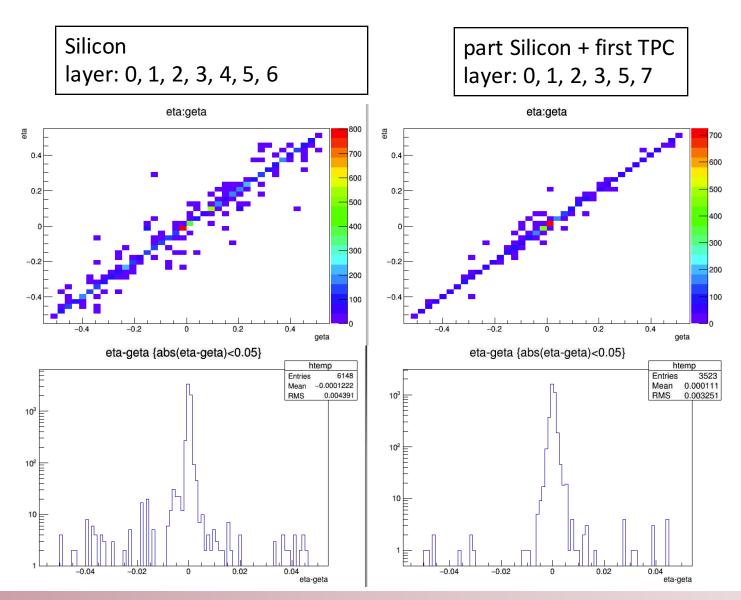
Seeding: $\Delta \phi$





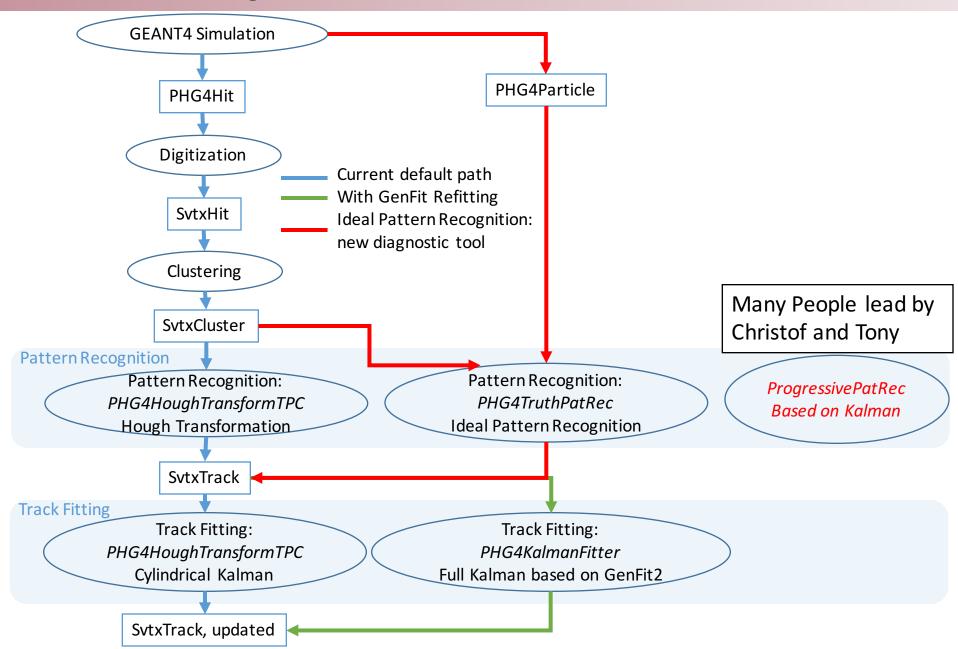


Seeding: $\Delta \eta$



Backups

sPHENIX tracking



Track updater with one measurement

PHGenFit::Track

genfit:::Track

vector::<AbsTrackRep>

TVectorD stateSeed_; // 6D: position, omentum TMatrixDSym covSeed ; // 6D

Only affect the starting TrackPoint => trackPointID == 0

vector::<TrackPoint>
= > map< AbsTrackRep*, AbsFitterInfo* >

Where measurements and Kalman Fitter Info resides

maps::<AbsTrackRep*, FitStatus>

Fitting Status: converged? chi2?



updateOneMeasurementKalman(
vector<PHGenFit::Measurement*>& measurements,
map<double, PHGenFit::Track*>& incr_chi2s_new_tracks
)

return a map incr_chi2 ⇒ new Track



genfit:: Measured State On Plane * extrapolate To Cylinder (...)

extrapolation now works with tracks without fitting